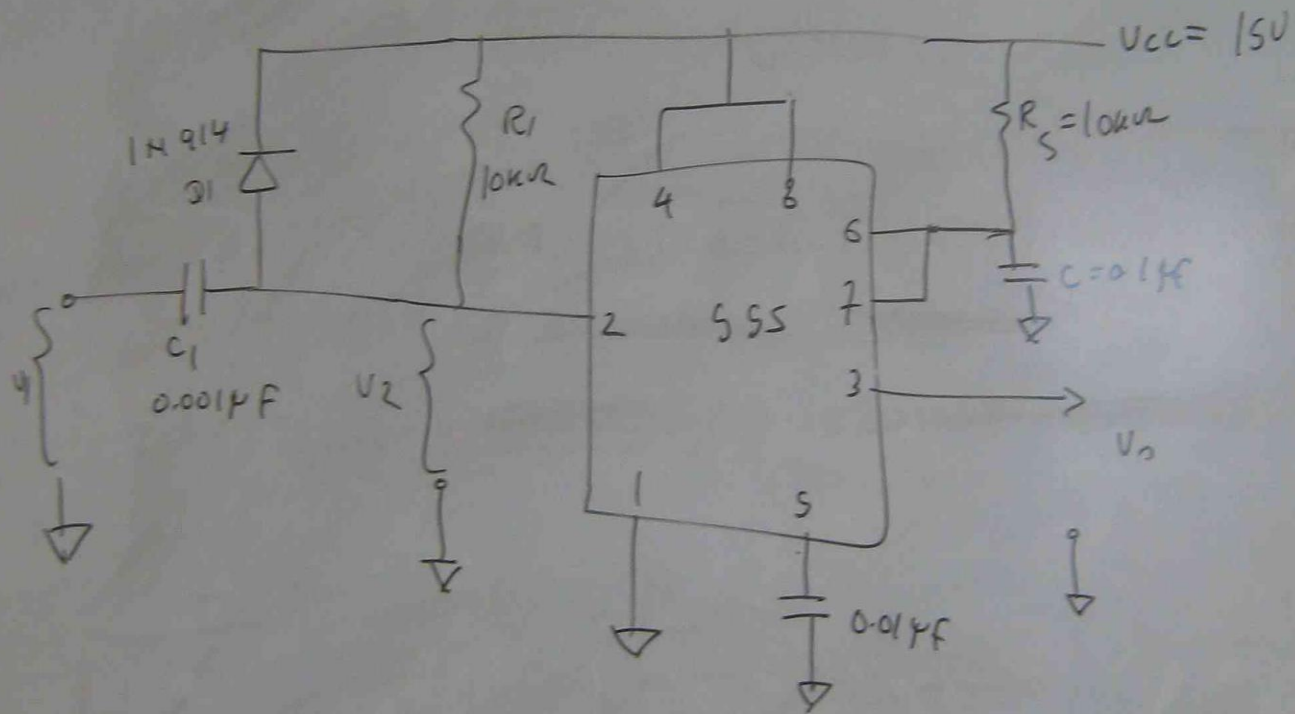
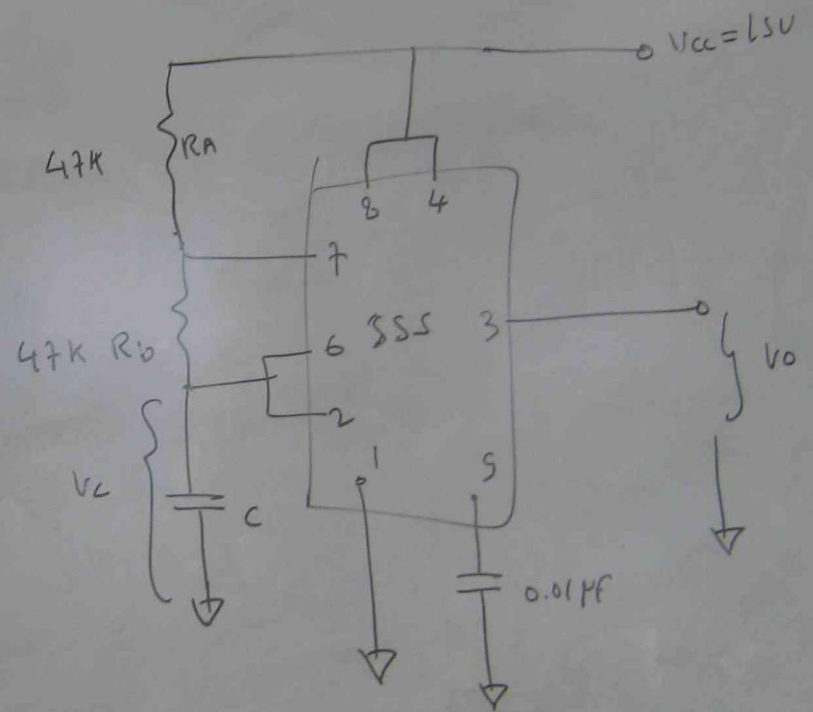
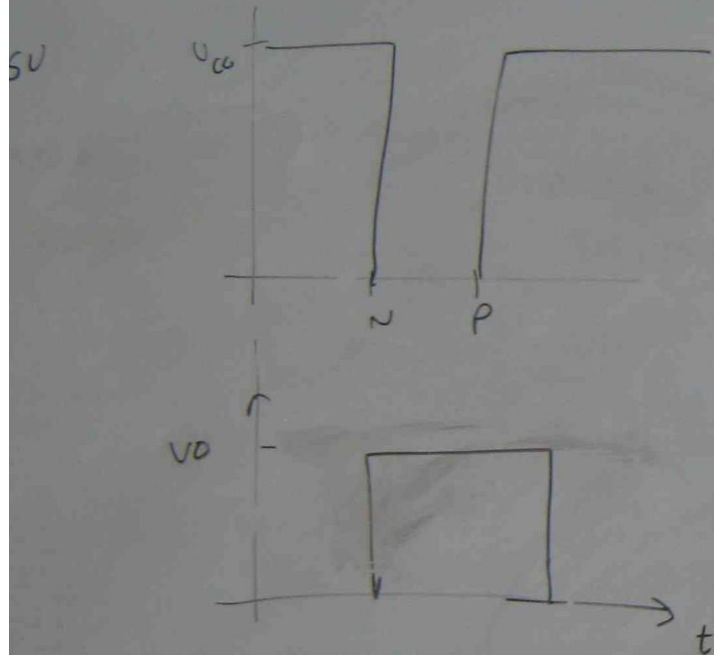


# MONOSTABLE CIRCUIT



$$t = \frac{1}{f}$$



$$t = \frac{1}{f}$$

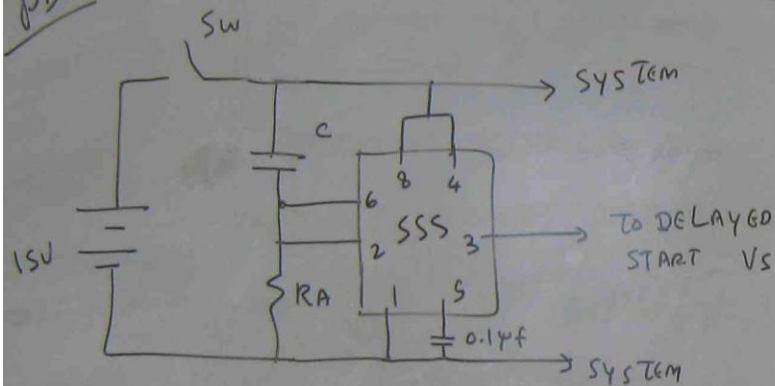
$$T = t_{\text{High}} + t_{\text{Low}}$$

$$t_{\text{High}} = 0.69 (R_A + R_B) C$$

$$t_{\text{Low}} = 0.69 R_B C$$

# CALCULATION OF POWER ON TIME DELAY

pb



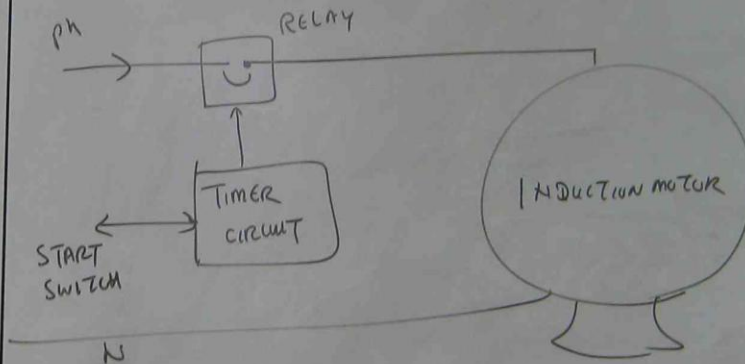
FOR THE ABOVE TIMER CIRCUIT, CALCULATE ON TIME DELAY GIVEN  $R_A = 820K$   
 $C = 2.2\mu f$

SKETCH OUT PUT PULSE.

$$T = 1.1 R_A C$$

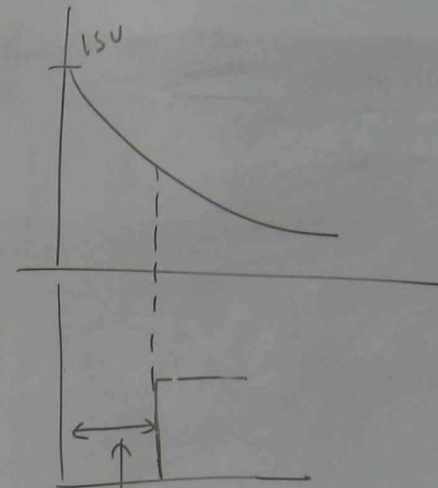
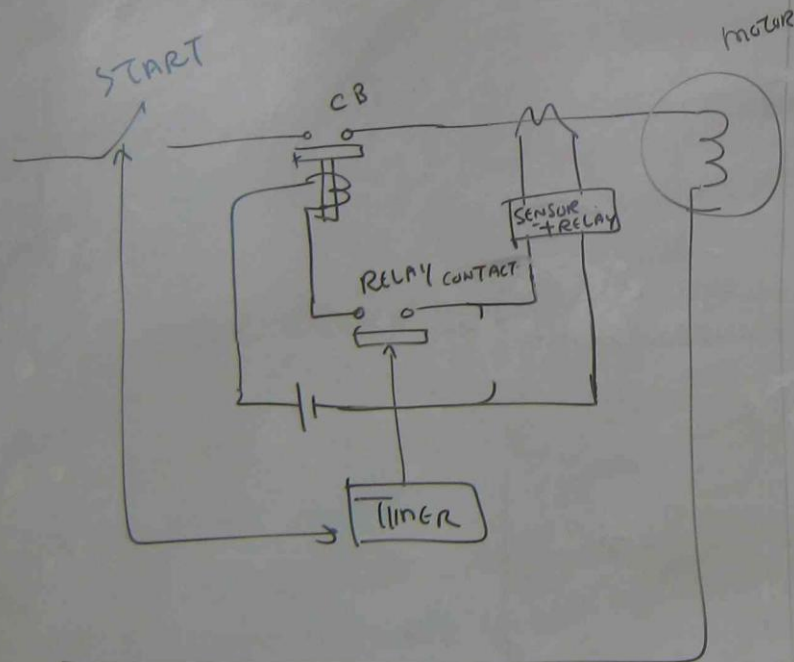
$$T = 1.1 \times 820 \times 10^3 \times 2.2 \times 10^{-6}$$

$$= 1.98 \text{ sec} \approx \underline{\underline{2 \text{ sec}}}$$



TIMER CIRCUIT IS APPLIED FOR MOTOR CONTROL RELAY. AT STARTING TIME, MOTOR CURRENT IS USUALLY HIGH. THE TIMER CIRCUIT CAUSES PROTECTIVE CIRCUIT TO IGNORE STARTING CURRENT WITH IN TIME SETTING. IF MOTOR CURRENT IS STILL HIGH AFTER HAVING

PASSED THE TIME DELAY, THEN THE PROTECTIVE RELAY EXECUTES TO PROTECT THE MOTOR FROM OVER CURRENT.



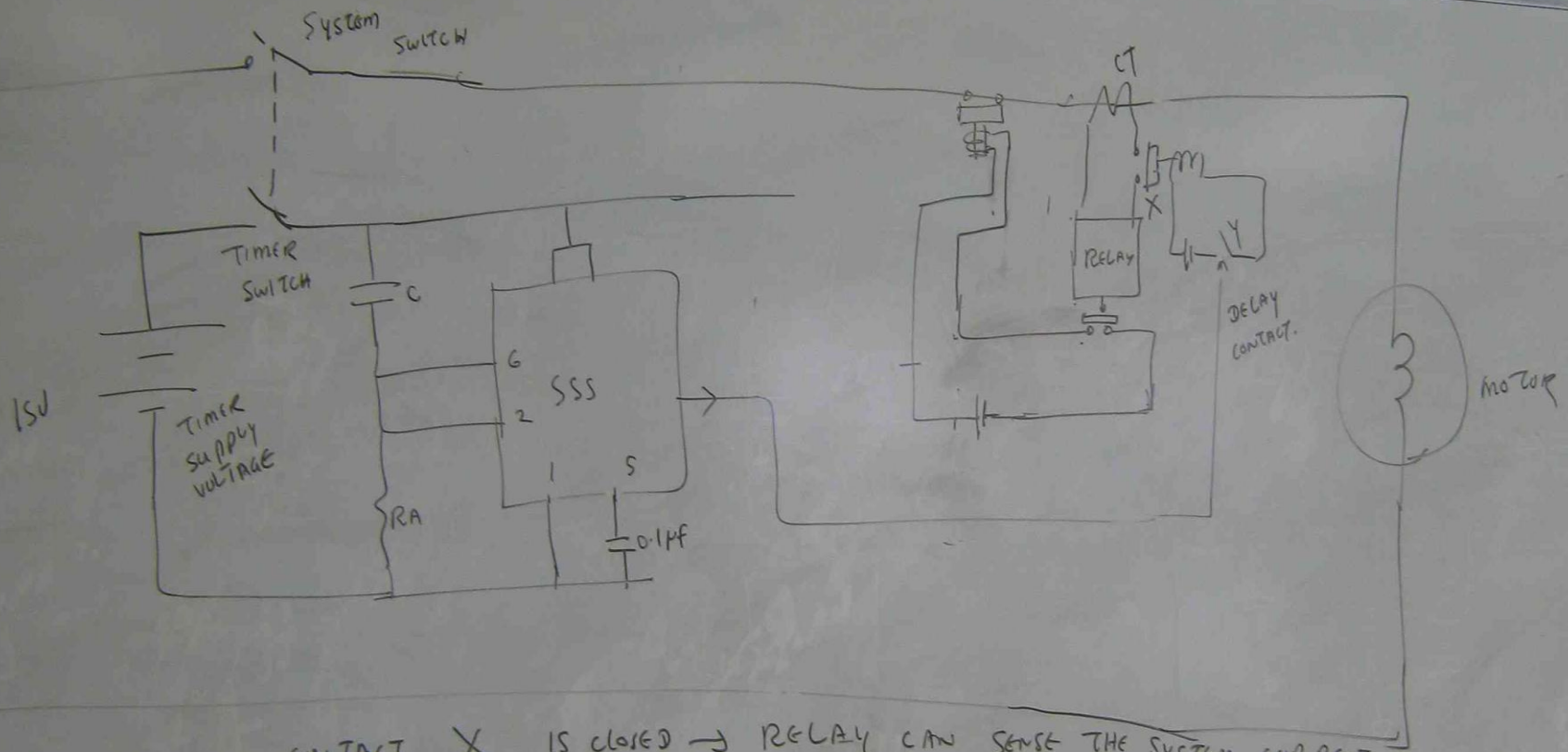
TIME DELAY  $T = 1.1 R_A C$

BY THIS WAY, THE RELAY CAN IGNORE MOTOR STARTING CURRENT RISE.

TIMER PREVENT THE RELAY CONTACT TO CLOSE WHEN THE MOTOR START SWITCH IS CLOSED.

MOTOR START SWITCH IS ALSO ATTACHED TO TIMER





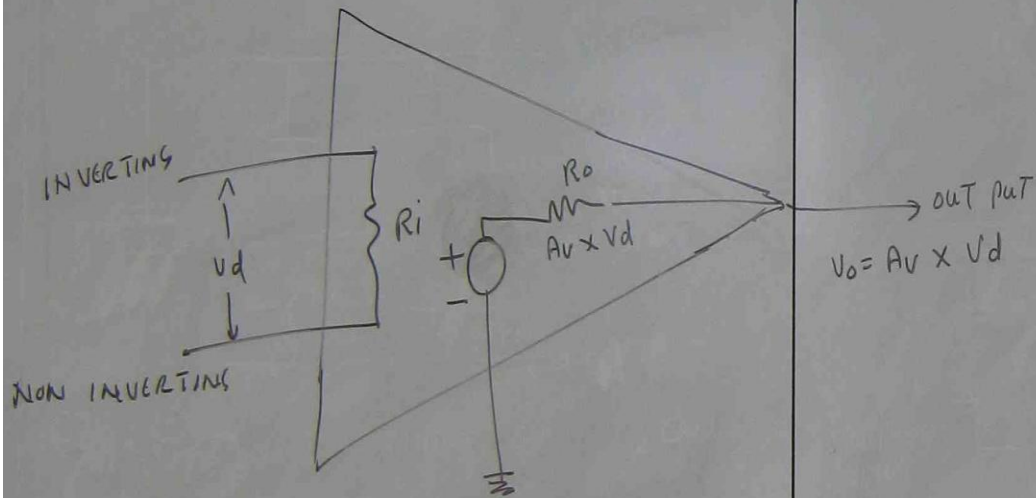
CONTACT X IS CLOSED  $\rightarrow$  RELAY CAN SENSE THE SYSTEM CURRENT

BUT CONTACT X IS INSTANTLY NOT CLOSED BECAUSE TIME DELAY

CONTACT Y OPERATED BY SSS TIMER PREVENTS IT TO DO SO.

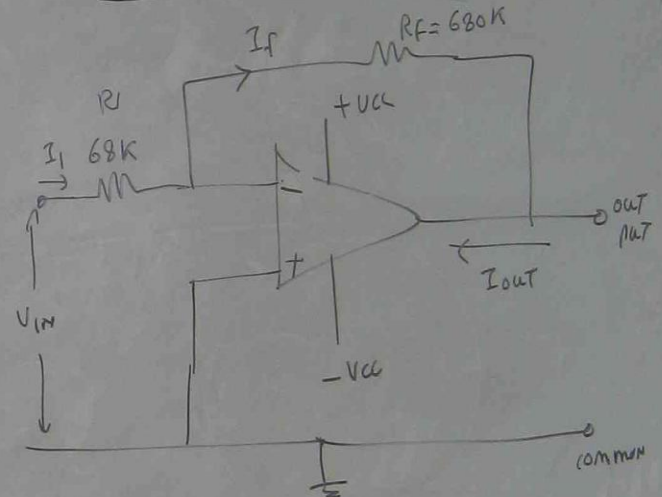
SSS TIMER WAITS FOR SOME TIME UNTIL SYSTEM STARTING CURRENT FALLS TO NORMAL.

# OPERATIONAL AMPLIFIER CIRCUIT (1)

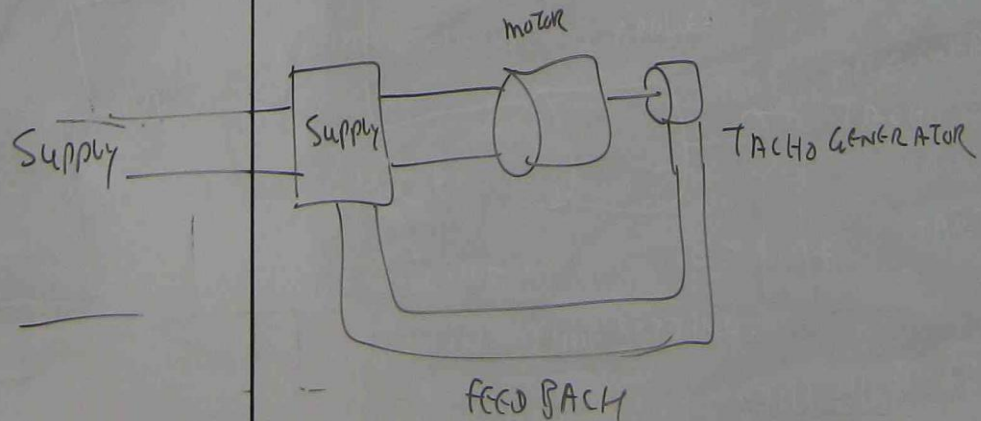


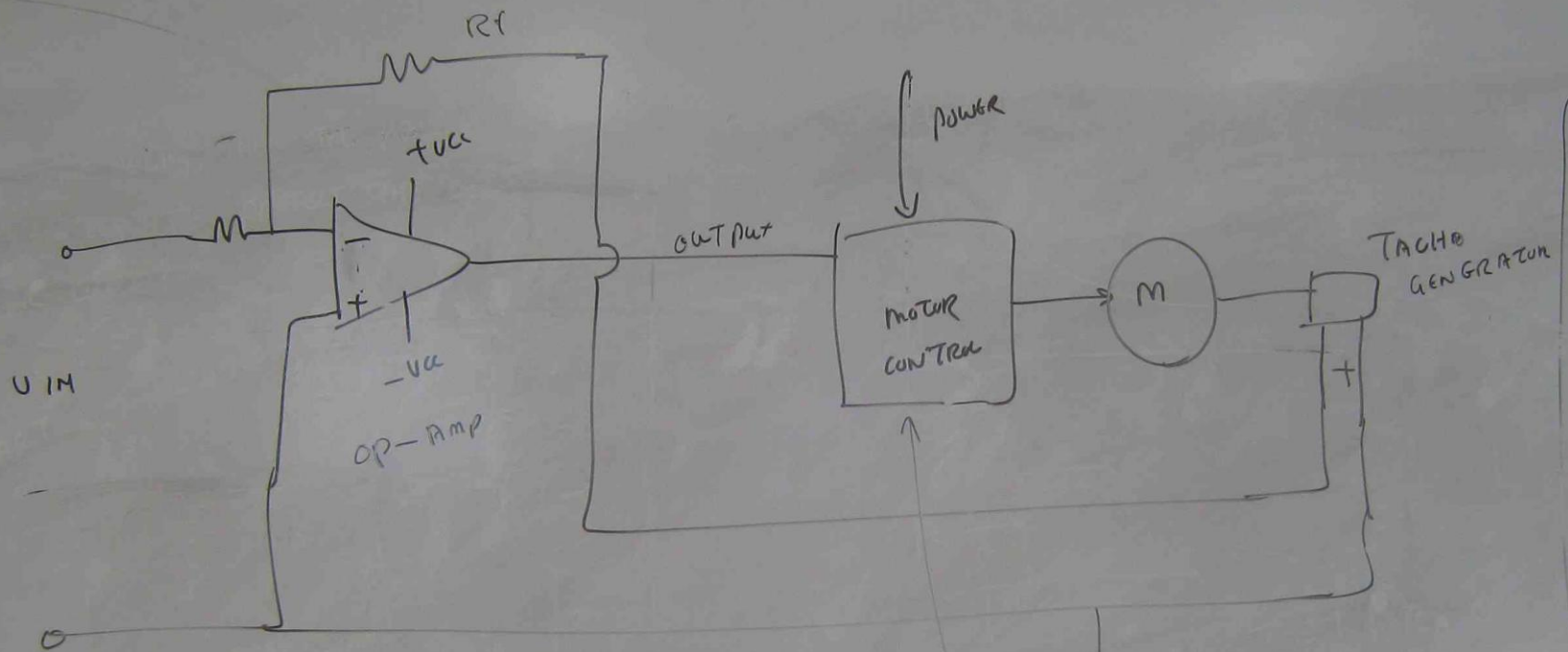
EQUIVALENT CIRCUIT OF  
OP-AMP

## IDEAL INVERTING AMPLIFIER

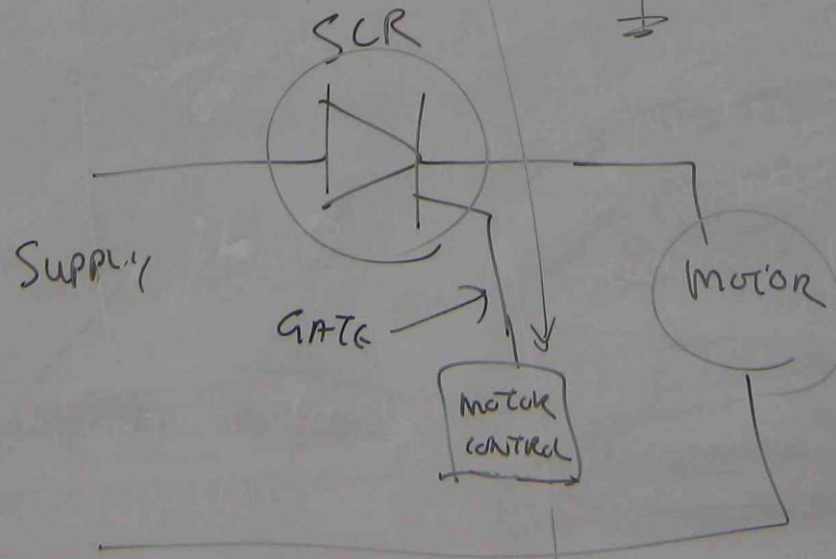


FEED BACK FACTOR  $B = \frac{R_i}{R_i + R_f}$





SCR  
SILICON CONTROL  
RECTIFIER



OP-AMP CIRCUIT CONTROL THE MOTOR CONTROL  
MODULE WHICH INCLUDES SCR (ELECTRONIC  
SWITCHING DEVICE).

MOTOR SPEED IS SENSED BY TACHO GENERATOR ATTACHED  
TO MOTOR SHAFT.

WHEN MOTOR IS OVER SPEED, SUCH SPEED IS SENSED  
AND PROPORTIONAL VOLTAGE IS PRODUCED.

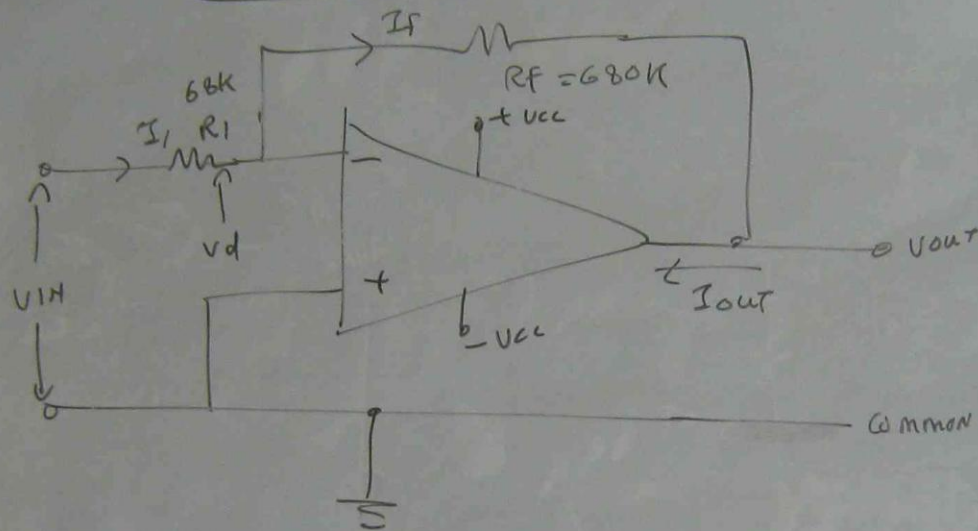
THIS VOLTAGE IS THEN FED BACK TO OP-AMP

(-) TERMINAL & IT IS COMPARED WITH REFERENCE  
VOLTAGE APPLIED TO (+) TERMINAL.

THE DIFFERENCE IS THEN AMPLIFIED &  
SENT TO CONTROL DEVICE



# INVERTING Amplifier



$$V_{OUT} = -I_1 R_F$$

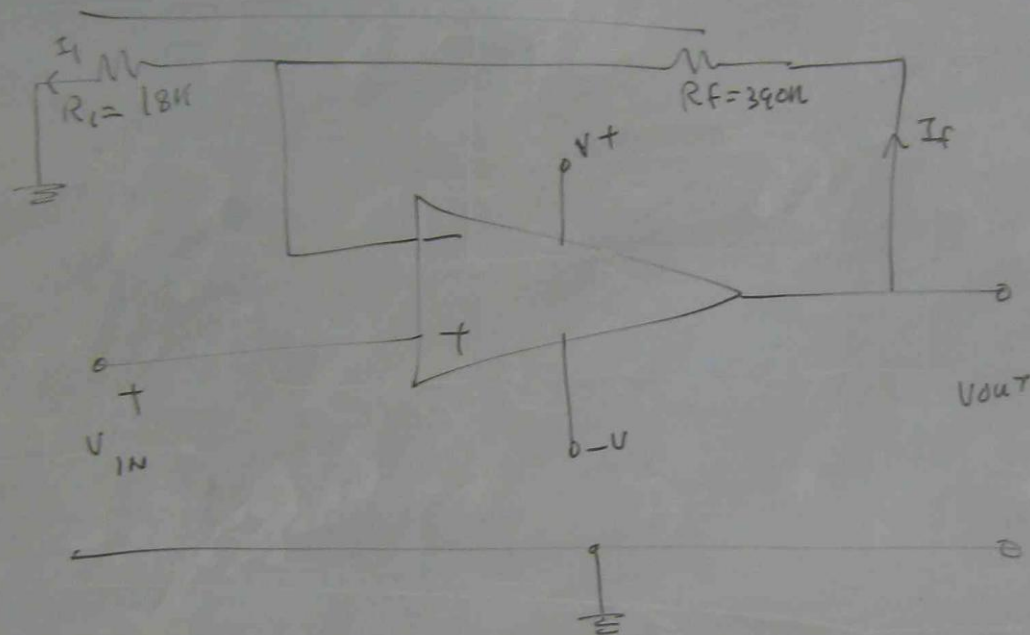
$$I_1 = \frac{V_{IN}}{R_1}$$

$$A_V = \frac{V_{OUT}}{V_{IN}}$$

$$I_1 = I_f$$

$$V_{RF} = I_f R_f - I_1 R_f$$

# NON INVERTING Amplifier



$$V_{IN} = V(+) = V(-)$$

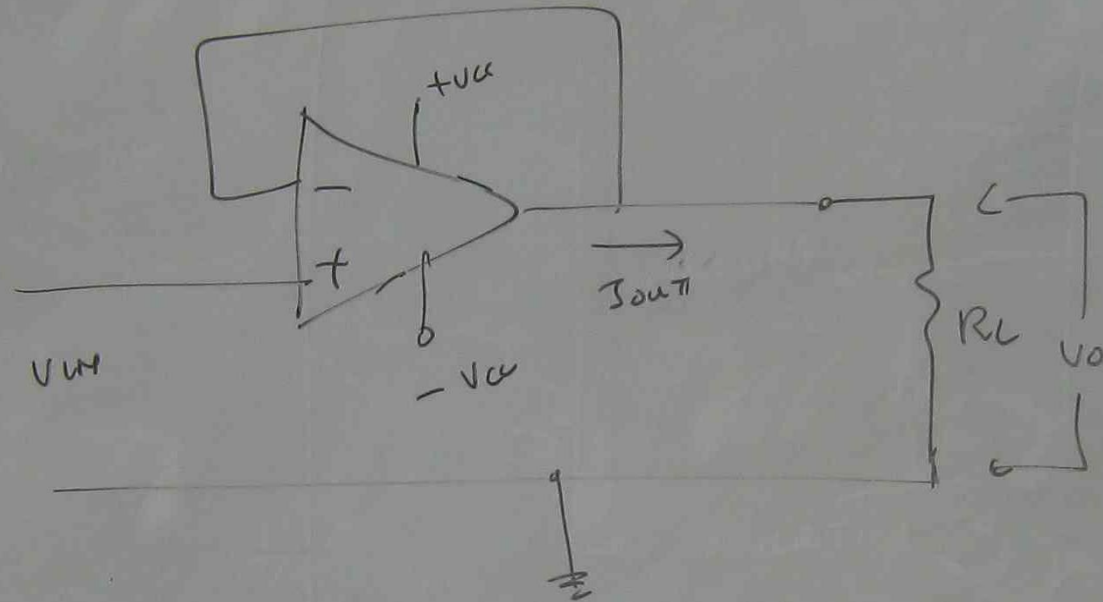
$$I_1 = I_F$$

$$V_{OUT} = V_{R_1} + V_{R_F}$$

$$A_V = \frac{V_{OUT}}{V_{IN}}$$

$$A_V = \frac{R_F}{R_1} + 1$$

## VOLTAGE FOLLOWER

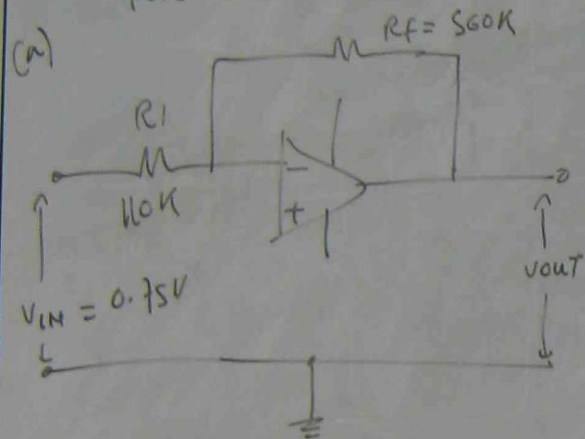


$$V_{in} = V_{(+)} - V_{(-)} = V_{out}$$

# PROBLEMS

ASSUMING IDEAL OP-AMPS. DETERMINE THE VOLTAGE GAIN AND OUTPUT VOLTAGE

FOR EACH CIRCUIT

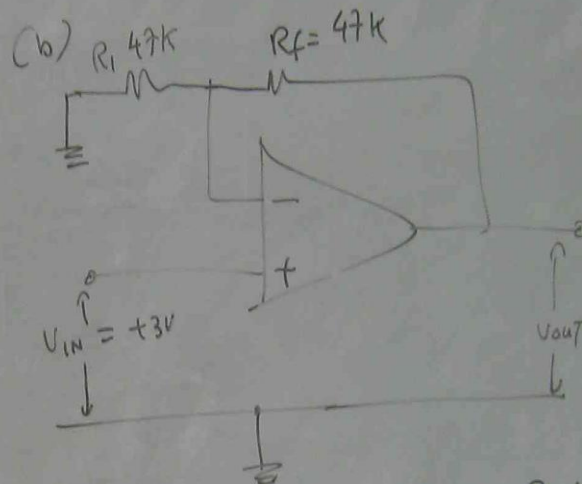


$$(a) I_1 = \frac{V_{IN}}{R_1} = \frac{0.75}{110k} = 6.8 \times 10^{-6} \text{ Amp}$$

$$V_{OUT} = -I_1 R_f = -6.8 \times 10^{-6} \times 560 \times 10^3 = -3.8V$$

$$|V_{OUT}| = 3.8V$$

$$A_v = \frac{V_{OUT}}{V_{IN}} = \frac{3.8}{0.75} = 5.06$$



$$A_v = \frac{R_f}{R_1} + 1$$

$$= \frac{47}{47} + 1 = 2$$

$$V_{OUT} = A_v \times V_{IN}$$

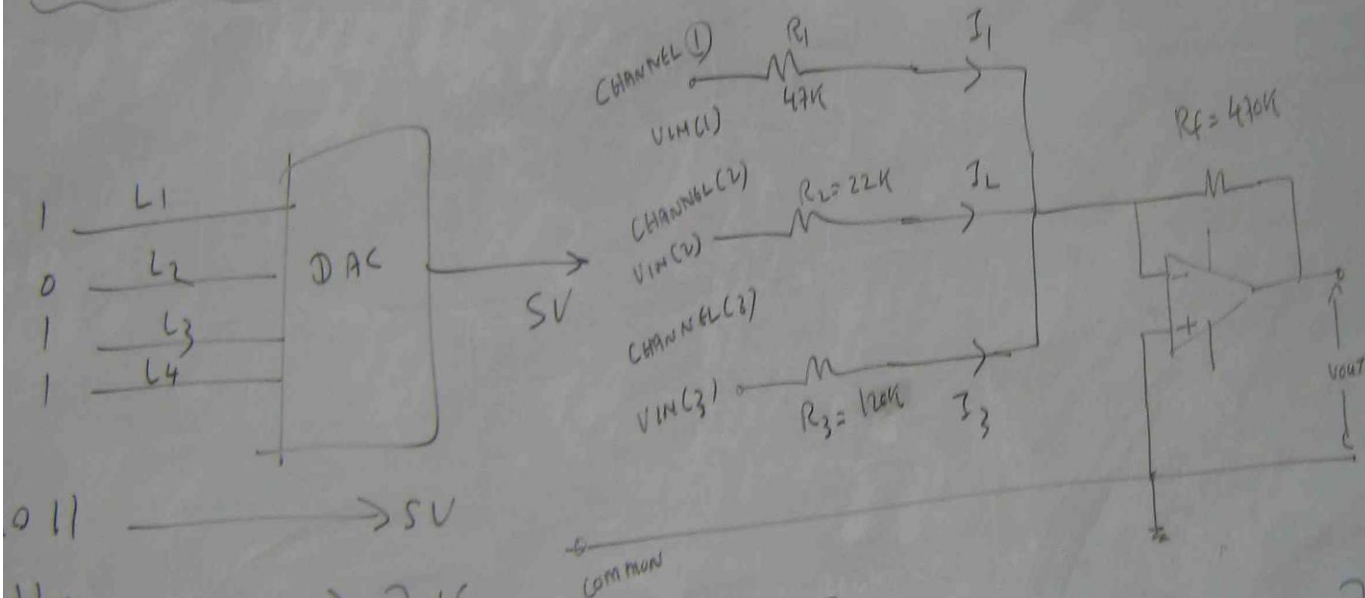
$$= 2 \times 3$$

$$= 6V$$



# OPERATIONAL AMPLIFIER CIRCUIT (2)

## THE IDEAL INVERTING SUMMER AMPLIFIER



$$V_o = - \left[ \frac{R_f}{R_1} V_1 + \frac{R_f}{R_2} V_2 + \frac{R_f}{R_3} V_3 \right]$$

$$V_{rms} = \sqrt{\frac{V_1^2 + V_2^2 + V_3^2}{2}}$$

ph

FOR THE GIVEN CIRCUIT

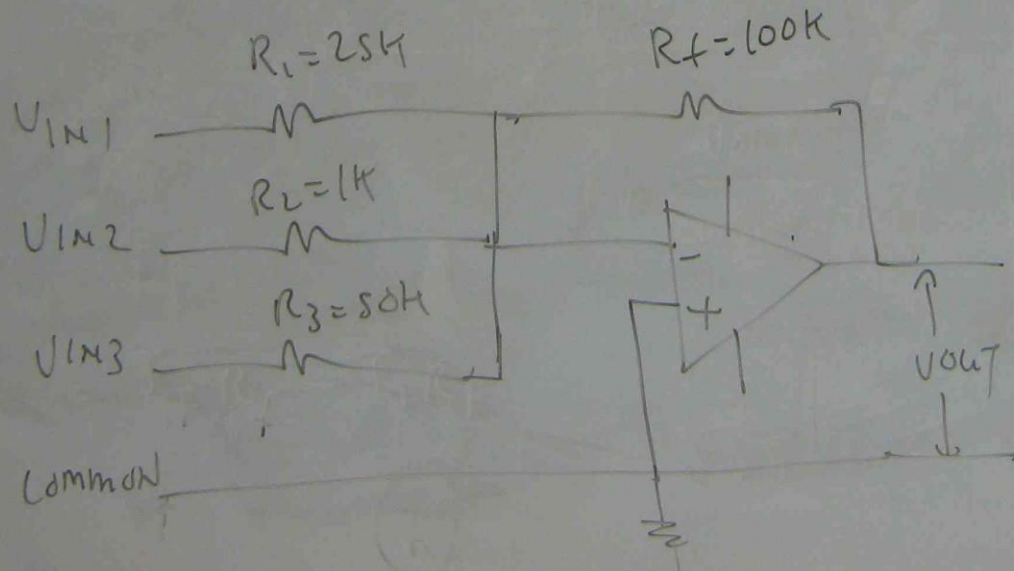
(a) CALCULATE THE VALUES OF THE CURRENT FLOWING IN EACH RESISTOR

$$I_{R_1}, I_{R_2}, I_{R_3}, I_f$$

(b) CALCULATE VOLTAGE GAIN OF EACH INPUT CHANNEL

(c) CALCULATE OUT PUT VOLTAGE GIVEN THAT

$$V_{IN1} = 0.4V, V_{IN2} = -0.1V, V_{IN3} = +5V$$



$$(a) \quad I_{R_1} = \frac{V_{IN1}}{R_1} = \frac{0.4}{25k} = 0.016 \text{ mA}$$

$$I_{R_2} = \frac{V_{IN2}}{R_2} = \frac{-0.1}{1k} = -0.1 \text{ mA}$$

$$I_{R_3} = \frac{V_{IN3}}{R_3} = \frac{5}{50k} = 0.1 \text{ mA}$$

$$I_f = I_{R_1} + I_{R_2} + I_{R_3} = 0.016 + (-0.1) + 0.1 = 0.016 \text{ mA}$$

$$(b) \quad A_{V1} = \frac{R_f}{R_1} = \frac{100}{25} = 4$$

$$A_{V2} = \frac{R_f}{R_2} = \frac{100}{1} = 100$$

$$A_{V3} = \frac{R_f}{R_3} = \frac{100}{50} = 2$$

(c)

$$V_o = - \left[ \frac{R_f}{R_1} V_1 + \frac{R_f}{R_2} V_2 + \frac{R_f}{R_3} V_3 \right]$$

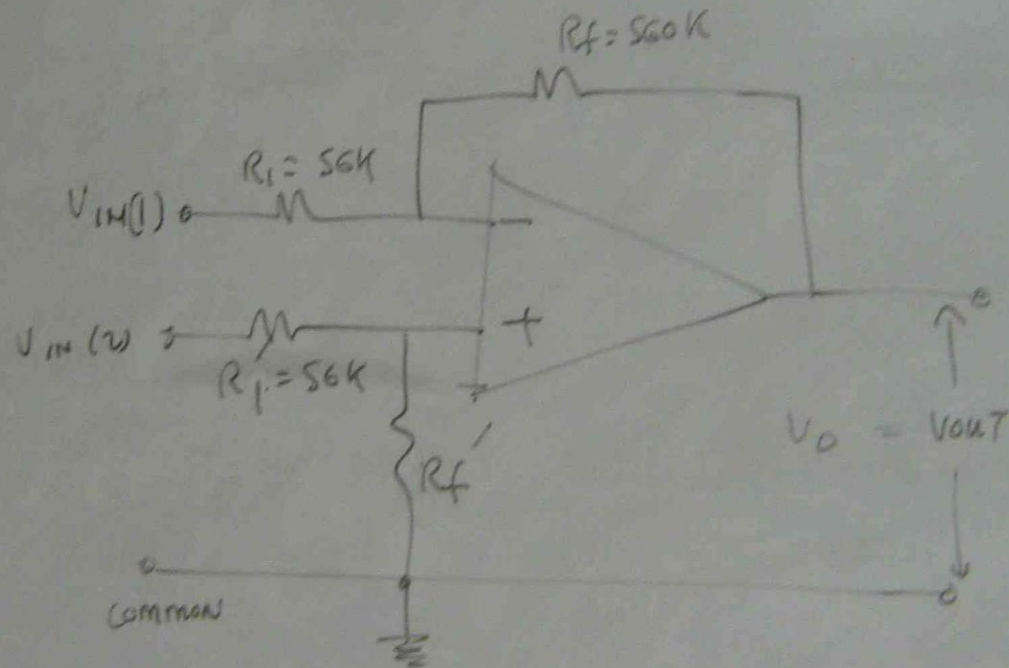
$$= - \left[ 4 \times 0.4 + 100 \times (-0.1) + 2 \times 5 \right]$$

$$= - \left[ 1.6 - 10 + 10 \right]$$

$$= -1.6 \text{ V} \quad \text{X}$$



# IDEAL DIFFERENTIAL AMPLIFIER



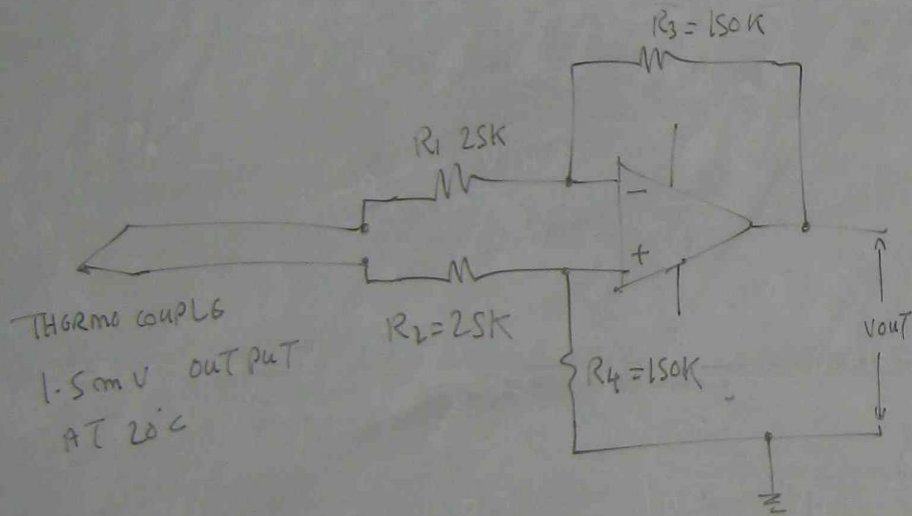
$$V_O = \frac{R_f}{R_1} [V_{IN2} - V_{IN1}]$$

ph

FOR THE GIVEN CIRCUIT,

(a) CALCULATE THE DIFFERENTIAL VOLTAGE GAIN OF THE CIRCUIT

(b) CALCULATE THE OUTPUT VOLTAGE FOR THE INPUT VOLTAGE GIVEN ON THE CIRCUIT



$$V_o = \frac{R_f}{R_1} [V_{IN2} - V_{IN1}]$$

$$R_f = R_3 = 150K$$

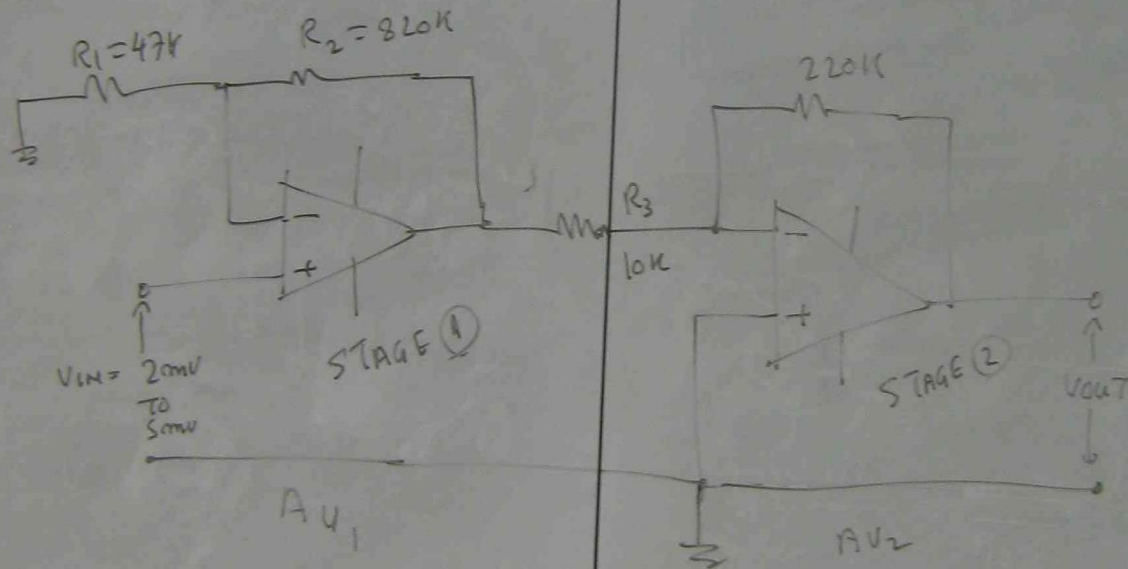
$$R_1 = 25K$$

$$V_{IN2} - V_{IN1} = 1.5mV$$

$$(b) \quad V_o = \frac{150}{25} [1.5mV] = 9mV$$

$$(a) \quad A_v = \frac{V_o}{V_{IN}} = \frac{9mV}{1.5mV} = 6$$

# CASCADING OPERATIONAL AMPLIFIER CIRCUITS



$$A_{V \text{ TOTAL}} = A_{V_1} \times (-) A_{V_2}$$

$$A_{V_1} = 1 + \frac{R_f}{R_1} \text{ (NON INVERTING)}$$

$$A_{V_2} = \frac{R_f}{R_1} \text{ (INVERTING)}$$

$$\text{STAGE ① } R_f = R_2 = 820k$$

$$R_1 = 47k$$

$$\text{STAGE ② } R_f = 220k$$

$$R_1 = R_3 = 10k$$

$$A_{V1} = 1 + \frac{820}{47} = 18.44$$

$$A_{V2} = \frac{220}{10} = 22$$

$$A_{V\text{-TOTAL}} = 18.44 \times (-) 22 \\ = (-) 406$$

$$V_{OUT} = A_{V\text{-TOTAL}} \times V_{IN} \\ = 406 \times 2 \text{ mV}$$

$$= 812 \text{ mV}$$

$$= 0.812 \text{ V}$$

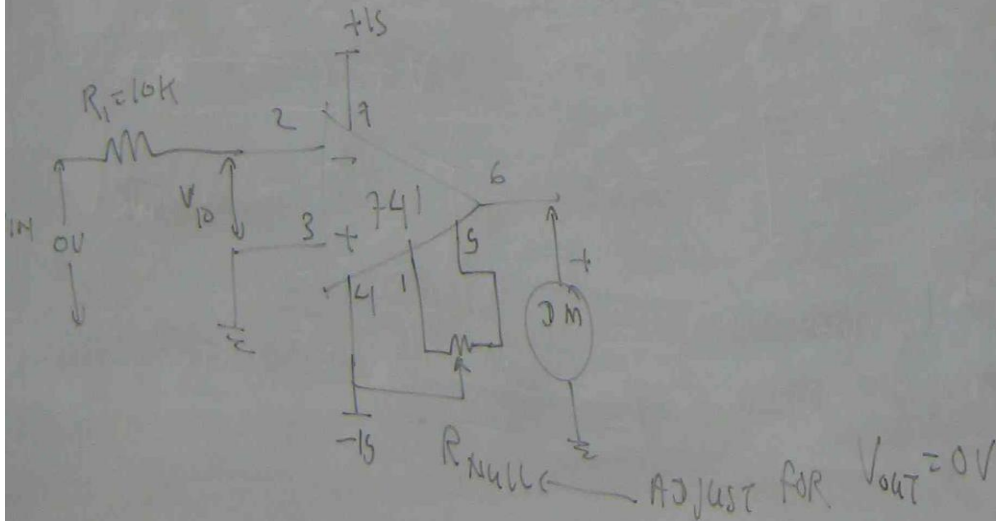


## LIMITATIONS OF OPERATIONAL AMPLIFIERS

OPERATIONAL AMPLIFIERS HAVE PRACTICAL LIMITATIONS THAT RESTRICT THEIR FREQUENCY RESPONSE, OUTPUT VOLTAGE ACCURACY, THERMAL STABILITY AND THEIR ABILITY TO FOLLOW THE INPUT VOLTAGE. APPLYING NEGATIVE TO ANY AMPLIFIER CAN IMPROVE THEIR STABILITY, WIDEN THE BANDWIDTH, RAISE THE INPUT RESISTANCE AND LOWER THE OUTPUT RESISTANCE, BUT AT THE EXPENSE OF OVER ALL VOLTAGE GAIN.

## THE INPUT OFFSET VOLTAGE

IT IS THE DC DIFFERENTIAL INPUT VOLTAGE THAT EXISTS INTERNALLY BETWEEN THE INVERTING AND NON INVERTING TERMINALS OF A PRACTICAL OP-AMP.



## INPUT BIAS CURRENT

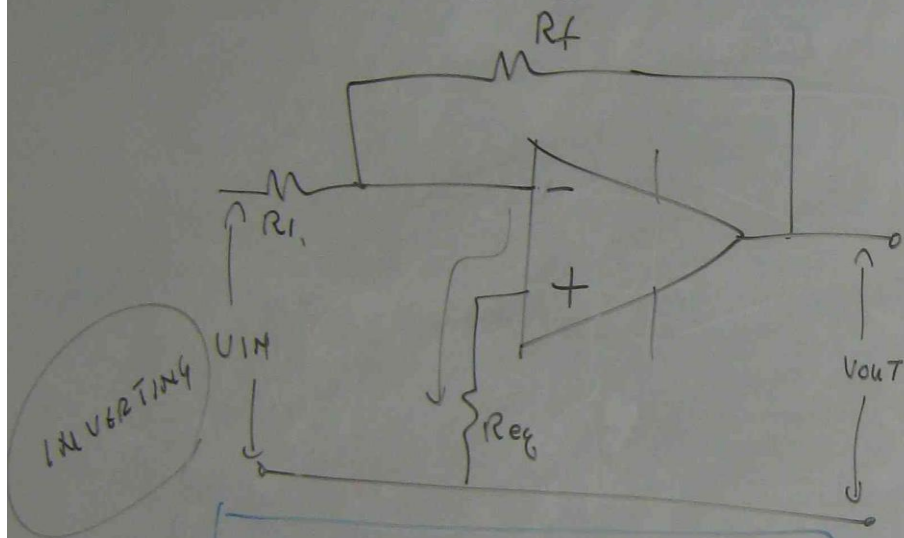
$$I_B = \frac{I_{B1} + I_{B2}}{2}$$

$I_B$  = INPUT BIAS CURRENT

$I_{B1}$  = DC BIAS CURRENT INTO NON INVERTING TERM.

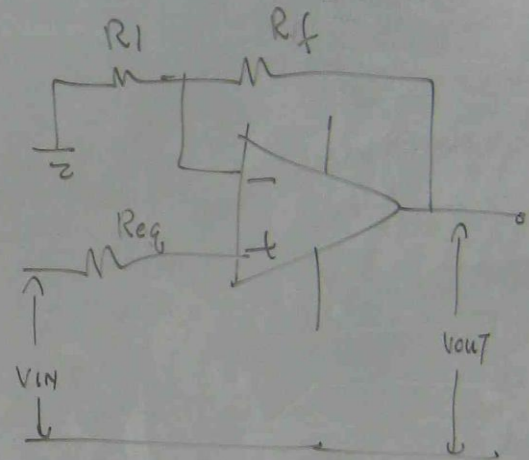
$I_{B2}$  = DC BIAS CURRENT INTO INVERTING TERM.

## OFF SET MINIMIZING RESISTOR & INPUT OFF SET CURRENT



$$R_{eq} = \frac{R_1 R_f}{R_1 + R_f} = R_1 \parallel R_f$$

OFFSET MINIMIZING  
RESISTANCE



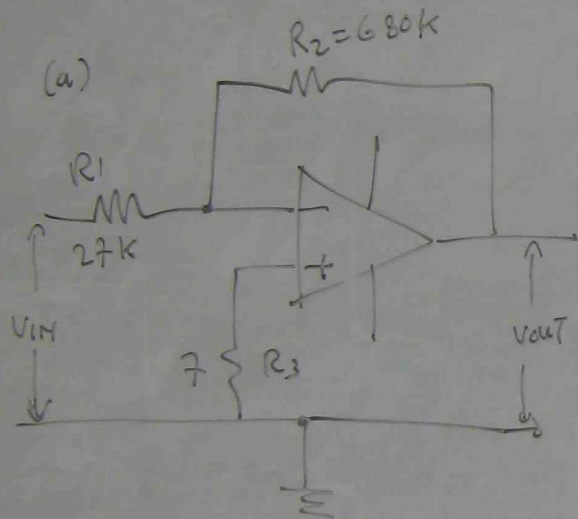
NON INVERTING

### INPUT OFFSET CURRENT

DIFFERENCE IN THE CURRENTS INTO  
THE TWO INPUT TERMINALS WHEN  
THE OUT PUT IS AT ZERO

ph

FOR THE GIVEN CIRCUITS, DETERMINE THE VALUE OF THE OFFSET MINIMIZING RESISTOR.

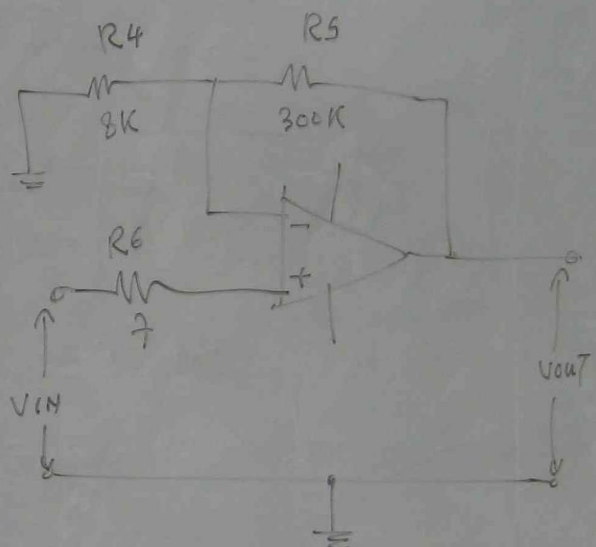


$$R_f = 680k \quad (R_2)$$

$$R_1 = 27k$$

$$R_{eq} = \frac{R_f R_1}{R_f + R_1} = \frac{680 \times 27}{680 + 27}$$

(b)



$$R_1 = R_4 = 8k$$

$$R_f = R_5 = 300k$$

$$R_{eq} = \frac{300 \times 8}{300 + 8}$$

### COMMON MODE REJECTION RATIO

IDEAL OPERATIONAL AMPLIFIER ONLY AMPLIFIES THE INPUT VOLTAGE AND IT SHOULD COMPLETELY REJECT THE COMMON MODE INPUT VOLTAGES CAUSED BY NOISE.

$$\text{CMRR (COMMON MODE REJECTION RATIO)} = \frac{A_d}{A_c} \quad (\text{OR}) \quad 20 \log \frac{A_d}{A_c} \quad (1)$$

### NOISE IN OUTPUT VOLTAGE

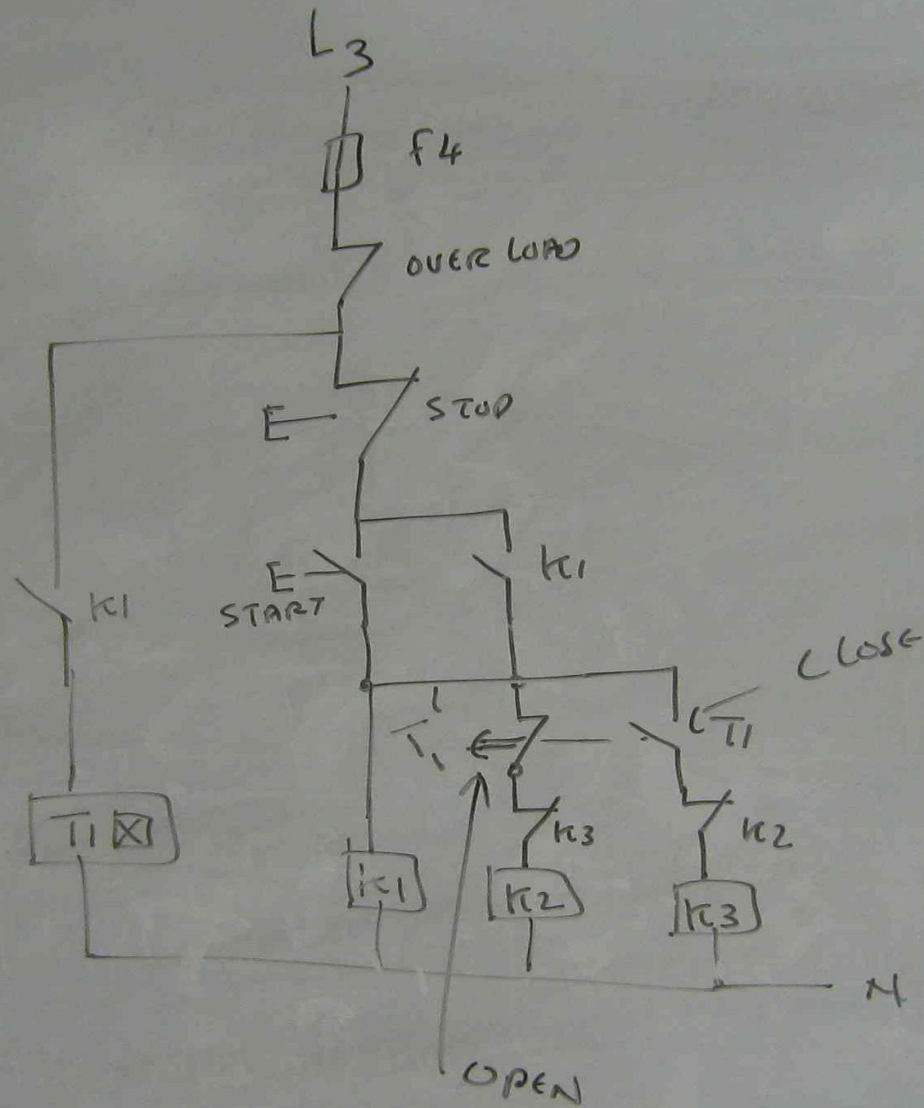
UNWANTED ELECTRICAL <sup>SIGNAL</sup> PRESENT IN OUTPUT SIGNALS ARE CLASSIFIED AS NOISE. NOISE CAN PRESENCE FROM 0.01 Hz TO FREQUENCIES OVER 1 MHz.

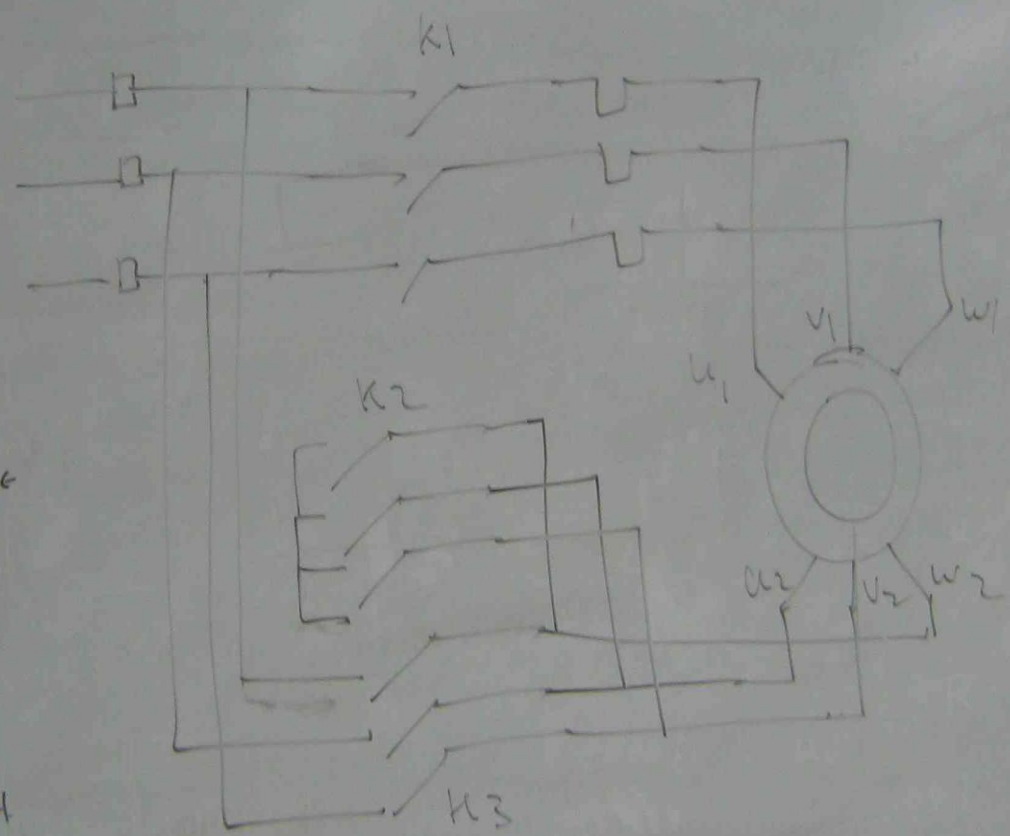
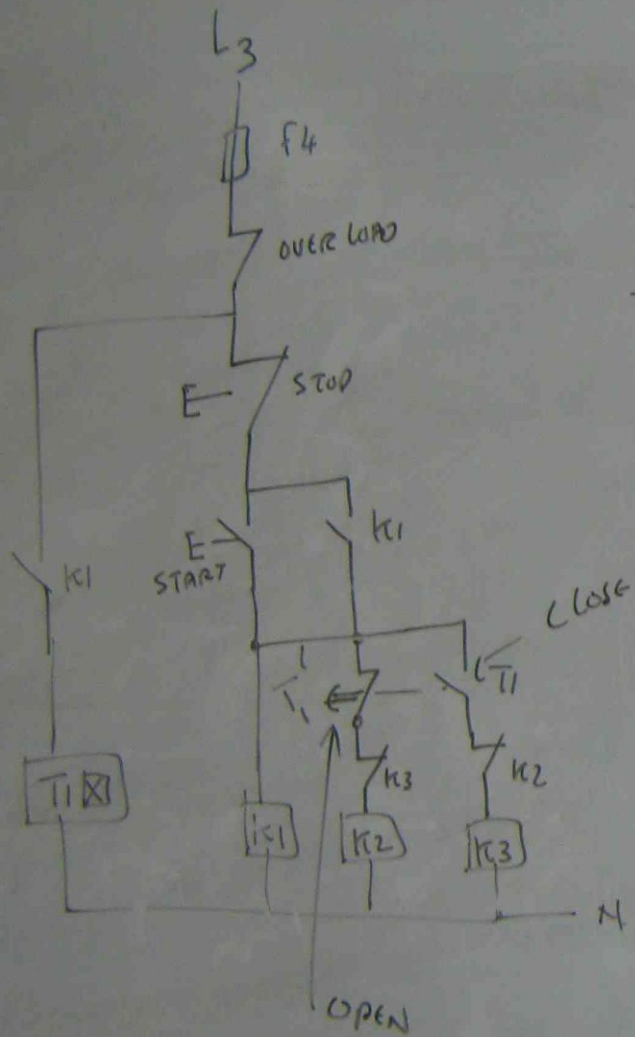
741 op amp  $\rightarrow$  NOISE 2  $\mu$ V

TO REDUCE THE NOISE, CAPACITOR IS CONNECTED IN PARALLEL WITH  $R_f$ .

$$\text{NOISE GAIN} = \frac{R_f}{R_i} + 1$$







OPEN TRANSITION X | STARTER

— WHEN START IS PRESSED,  $K_1$  COIL IS ENERGIZED.

—  $K_1$  CONTACTS ARE CLOSED

— TIMER  $T_1$  IS ENERGIZED AS  $K_1$  CONTACT WHICH IS CONNECTED IN SERIES WITH IT IS CLOSED

—  $K_2$  COIL IS ENERGIZED AS THE CURRENT FLOWS THROUGH  $K_1$  &  $K_3$  NORMALLY CLOSED CONTACTS.

— WHEN  $K_2$  COIL IS ENERGIZED,  $K_2$  CONTACTS ARE CLOSED AND MOTOR STARTS WITH  $\Delta$  CONNECTION

— AFTER SOME TIME, TIMER OPEN  $T_1$  & CLOSE  $T_1$

— BY OPENING  $T_1$ ,  $K_2$  IS DE-ENERGIZED AND  $K_2$  CONTACTS ARE OPEN.

— BY CLOSING  $T_1$ ,  $K_3$  COIL IS ENERGIZED AND  $K_3$  CONTACTS ARE CLOSED.

MOTOR RUNS WITH  $\Delta$ . AS  $K_3$  CONTACT CONNECTED IN SERIES WITH  $K_2$  COIL IS OPEN,  $K_2$  COIL CAN NOT CLOSE.